Cosmological solutions from multi-measure model

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Recall the darkon-case

The equations in the darkon case are ([1, 2, 3]): **A cubic equation for** $y = \dot{u}$: $y^3 + 3ay + 2b = 0$ with $\mathbf{a} = -\frac{2}{3-24\alpha M_0}$ and $\mathbf{b} = -\frac{2\alpha p_u}{a(t)^3(1-8\alpha M_0)}$. And **the Friedman equation for** a(t) – after rescaling time by $2|\alpha|/3 = 1$ and absorbing α into Hubble constant ($\bar{\rho} = 4|\alpha|\rho$):

$$\left(\frac{\dot{a}(t)}{a(t)}\right)^2 = \bar{\rho} = \left(\frac{1}{2}y^2 + \frac{\mathbf{b}}{\mathbf{a}}y - 1\right) \tag{1}$$

The asymptotics, corresponding to the dark energy term in the late universe, is:

$$\bar{\rho} \xrightarrow[a(t)\to\infty]{} \begin{cases} 1 \text{ for } \mathbf{a} > 0 \\ -\frac{3}{2}\mathbf{a} - 1 \text{ for } \mathbf{a} < 0 \end{cases}$$

We use as independent real solutions y_b (our basic solution) and y_s and integrate numerically Eq. (1) to find the evolution of the universe. Staicova & Stoilov, Mod. Phys. Lett. A, **32**, 1 (2017) Staicova & Stoilov, arXiv:1801.07133

Universes with or without phase transition

Let $\overline{\rho}$ the density corresponding to solution y_s ($\overline{\rho}$ corresponds to y_b). If for $t_1 = 0$, $\overline{\rho}(t_1) < 0$ but for $t_p > t_1$, it changes sign: $\overline{\rho}(a(t_p)) = 0$. Then, for any moment $t > t_p$ we have two "states" of the Universe $\overline{\rho}$ and $\overline{\rho}$ such as:

$$0 \le \bar{\bar{\rho}} < \bar{\rho} \quad \text{for} \quad t \ge t_{\rho}. \tag{2}$$

This opens the possibility the Universe to undergo "phase transition".



Figure: Left:Graphics of the a(t) evolution for: $\mathbf{a} = -5.987$, $\mathbf{b} = \frac{-2.932}{a^3}$ (a) $\mathbf{a} = -1$, $\mathbf{b} = -\frac{2}{a^3}$ (b), $t_p = 1.5074$, $a_s(t_p) = 2.0825$ (b₂), $\mathbf{a} = -.5$, $\mathbf{b} = -\frac{0.5}{a^3}$ (c), Right: $b_{\pm} = \sum_{0}^{4} \pm c_i a^i + O(a^5)$, $c_i = [0.337906, 0.376679, -0.0251697, 0.00148545, 0.11272710^{-3}]$

The multi-measures model Guendelman, Nissimov and Pacheva 2014, 2016

The action of the model $S = S_{darkon} + S_{inflaton}$ is :

$$egin{aligned} S_{darkon} &= \int d^4 x \sqrt{-g}(R(g,\Gamma)) + \int d^4 x (\sqrt{-g} + \Phi(C)) L(u,Y) \ S_{inflaton} &= \int d^4 x \Phi_1(A) (R+L^{(1)}) + \int d^4 x \Phi_2(B) \left(L^{(2)} + rac{\Phi(H)}{\sqrt{-g}}
ight) \end{aligned}$$

where we have auxiliary fields $\Phi_i(X) = \frac{1}{3} \epsilon^{\mu\nu\kappa\lambda} \partial_\mu X_{\nu\kappa\lambda}$ and

$$L(u, X) = -\frac{1}{2}g^{\mu\nu}\partial_{\mu}u\partial_{\nu}u - W(u)$$

$$L^{(1)} = -\frac{1}{2}g^{\mu\nu}\partial_{\mu}\phi\partial_{\nu}\phi - V(\phi), V(\phi) = f_{1}e^{-\alpha\phi}$$

$$L^{(2)} = -\frac{b}{2}e^{-\alpha\phi}g^{\mu\nu}\partial_{\mu}\phi\partial_{\nu}\phi + U(\phi), U(\phi) = f_{2}e^{-2\alpha\phi}$$

From the equations of motion we obtain the following new constants:

$$L(u, Y) = -2M_0 = const, \frac{\Phi_2(B)}{\sqrt{-g}} = \chi_2 = const$$

 $R + L^{(1)} = -M_1 = const, L^{(2)} + \frac{\Phi(H)}{\sqrt{-g}} = -M_2 = const$

and the effective potential:

$$U_{eff}(\phi) = \frac{1}{4} \frac{(f_1 e^{-\alpha\phi} + M_1)^2}{\chi_2(f_2 e^{-2\alpha\phi} + M_2) - 2M_0} \text{ with asymptotics } U_- = \frac{f_1^2}{4\chi_2 f_2}, U_+ = \frac{1}{4} \frac{M_1^2}{\chi_2 M_2 - 2M_0}$$

The equations in FLRW metric

The system of equations we need to solve is:

$$v^{3} + 3av + 2b = 0 \text{ for } \mathbf{a} = \frac{-1}{3} \frac{V(\phi) + M_{1} - \frac{1}{2}\chi_{2}be^{-\alpha\phi}\dot{\phi}^{2}}{\chi_{2}(U(\phi) + M_{2}) - 2M_{0}}, \mathbf{b} = \frac{-p_{u}}{2a(t)^{3}(\chi_{2}(U(\phi) + M_{2}) - 2M_{0})}$$
(3)

$$\dot{a}(t) = \sqrt{\frac{\rho}{6}}a(t), \quad \rho_{=}\frac{1}{2}\dot{\phi}^{2}(1+\frac{3}{4}\chi_{2}be^{-\alpha\phi}v^{2}) + \frac{v^{2}}{4}(V+M_{1}) + \frac{3p_{u}v}{4a(t)^{3}}$$
(4)

$$\frac{d}{dt}\left(a(t)^{3}\dot{\phi}(1+\frac{\chi_{2}}{2}be^{-\alpha\phi}v^{2})\right)+a(t)^{3}(\alpha\frac{\dot{\phi}^{2}}{4}\chi_{2}be^{-\alpha\phi}v^{2}+\frac{1}{2}V_{\phi}v^{2}-\chi_{2}U_{\phi}\frac{v^{4}}{4})=0$$
(5)

The parameters of this system are 12:

 $\{\alpha, b_0, M_0, M_1, M_2, f_1, f_2, p_u, \chi_2\}$

Initial and boundary conditions:

I.
$$a(0) = 10^{-12}$$
, $\phi(0) = \phi_0$, $\dot{\phi}(0) = 0$ – initial conditions
II. $a(1) = 1$ – normalization
III. $a''(t) = 0$ – in 3 points

Constraints on the parameters:

$$\frac{f_1^2}{\chi_2 f_2}, >> \frac{M_1^2}{\chi_2 M_2 - 2M_0}$$

(6)

From [1, 2]: $|M_1| \sim M_{EW}^4, M_2 \sim M_{PI}^4, f_1 \sim f_2 \sim 10^{-8} M_{PI}^4$

Asymptotics

Limits for the equation of state (EOS) $w = p/\rho$:

$$\begin{array}{ccc} w & \xrightarrow[a(t)=0]{} & 1/3 \\ w & \xrightarrow[a(t)\to\infty]{} & -1 \end{array}$$

$$(7)$$

Due to a strong friction term, in the far future $(a(t) \rightarrow \infty, \dot{\phi}(t) \rightarrow 0)$:

$$\rho \to 0 \text{ for } \mathbf{a} > 0
\rho \to \frac{1}{4} \frac{(V(\phi) + M_1)^2}{\chi_2(U(\phi) + M_2) - 2M_0} \text{ for } \mathbf{a} < 0$$
(8)

where **b** $\xrightarrow[a(t)\to\infty]{}$ 0 and $v \to 0$ for **a** > 0 and $v \to \sqrt{-3a}$ for **a** < 0. The dynamically generated cosmological constant for **a** < 0

$$\Lambda_{eff} = M_1^2 / (8(\chi_2 M_2 - 2M_0)). \tag{9}$$

Considerations for the parameters

- c = 1, $G = 1/16\pi$ and $t_u = 1$, where t_u is the present day age of Universe. Thus, our mass unit is equal to $1.62 \times 10^{59} M_{Pl}$ where M_{Pl} is Plank mass.
- 2 The only limit on the parameters is $\frac{f_1^2}{\chi_2 f_2} >> \frac{M_1^2}{\chi_2 M_2 2M_0}$
- ullet $M_0 < 0$, so that $\mathbf{b} < 0$ and y is real

$$(0) = 0$$

• $b_0 > 0$ (problems with ρ otherwise)

Giving us the following cases:

• Case 1: $\chi_2 \sim 1$, $M_0 \sim -0.04$, $0 < M_2 << |M_0|$. For these parameters, using the value of the cosmological constant (≈ 3.6 in our units) one can easily obtain:

$$M_1 \sim 1.5.$$
 (10)

• Case 2: $\chi_2 \ll 1$, $M_0 \sim -0.01$, $M_2 = 4$ ($\gg |M_0|$). For these parameters the relation between χ_2 and M_1 becomes:

$$M_1 = 0.24\sqrt{2000\chi_2 + 10} \sim 0.76 \tag{11}$$

The evolution of the Universe in the [a, b] plane

Staicova & Stoilov, Mod. Phys. Lett. A, **32**, 1 (2017) Staicova & Stoilov, arXiv:1801.07133



Evolution of the parameters [a(t), b(t)] for the darkon (dash) and the inflaton (dot-dash).

The evolution of the Universe starts from $b \to -\infty$ and finishes at $b \to 0$ We have chosen the parameters in such a way that: $b = \frac{-p_u}{2a(t)^3(\chi_2(U+M_2)-2M_0)} < 0$. I.e $M_0 < 0$.

Numerical solutions



Figure: a) The effective potential. b) $\ddot{a}(t)$ and $w = p/\rho$, where UM is ultra-relativistic matter domination , EI – the early inflation, MD – the matter domination (MD) and LI – the late inflation.

Strong friction term on ϕ !



From asymptotical analysis: assuming $a(t) = e^{Ht}$, we obtain: $\phi(t) = C_1 + C_2 e^{-3Ht}$



Figure: The Universe evolution in case 1 ($\chi_2 = 1$, $M_0 = -0.04$, $M_1 = 1.5$, $M_2 = 0.001$). The parameters { $\alpha, b_0, \rho_{\mu}, f_1, f_2$ } are {1, 0.027, 7.7 × 10⁻⁹, 7, 10⁻³} (solid lines), {1.2, 0.021, 1.1 × 10⁻¹⁰, 6.76, 10⁻³} (dashed lines) and {1.4, 0.016, 3 × 10⁻¹², 6.35, 10⁻³} (dot-dashed lines).



(dot-dashed lines).

Main results (Staicova & Stoilov, arXiv:1806.08199)

A. One can construct a 4-stages Universe

- At $t_0 = 0$ we observe the EOS of ultra-relativistic matter with w = 1/3.
- 2 Initial inflation with EOS of dark energy $w \rightarrow -1$.
- Matter domination stage where w > -1/3 and $w \to 0$.
- Accelerated expansion with w < -1/3.

B. The model can be normalized to a(1) = 1, $t(MD \rightarrow LI) = 0.71$ and the effective cosmological constant

C. There is a strong friction term which stops the evolution of ϕ after certain moment.

D. There is an effect of "climbing-up" the potential

E. The slow-roll parameters in the periods of inflation

([0.017 - 0.460, 0.71 - 1] in Case 1 and [0.015 - 0.662, 0.71 - 1]) don't seems to satisfy the slow-roll conditions:

$$\epsilon = -\frac{\dot{H}}{H^2} \ll 1, \quad \eta = -\frac{\ddot{\phi}}{H\dot{\phi}} \ll 1.$$
(12)

Let's return to the effective potential

If one starts with inflaton equations of the type:

$$H^{2} = 8 \frac{\pi}{3m_{\rho l}^{2}} \left(\frac{1}{2} \dot{\phi}^{2} + V(\phi) \right)$$
(13) as:
1) $\ddot{\phi}(t) << 3H\dot{\phi} \rightarrow \eta = -\frac{\ddot{\phi}}{H\dot{\phi}}$
 $\ddot{\phi} + 3H\dot{\phi} + V'(\phi) = 0$ (14) 2) $\frac{\ddot{a}(t)}{a(t)} = \dot{H} + H^{2} = H^{2}(1-\epsilon) \rightarrow \epsilon = -\frac{\dot{H}}{H^{2}}$

If we write the inflaton equation in the form:

$$\left(v(t)^{2}A(t)+1\right)\ddot{\phi}(t) - \frac{1}{2}v(t)^{2}\alpha A(t)\dot{\phi}(t)^{2} + \left(3v(t)^{2}A(t)H + 2v(t)A(t)\dot{v}(t) + 3H\right)\dot{\phi}(t) - \frac{v(t)^{2}f_{1}\alpha}{2e^{\alpha\phi(t)}} + \frac{\chi_{2}f_{2}\alpha v(t)^{4}}{2e^{2\alpha\phi(t)}} = 0,$$
(15)

where $A(t) = \frac{b_0\chi_2}{2e^{\alpha\phi(t)}}$. If one uses the slow-roll approximation (neglecting the terms $\sim \dot{\phi}^2$, $\dot{\phi}^3$, $\dot{\phi}^4$ and A(t)), Eq. (15) simplifies to:

$$\ddot{\phi} + 3H\dot{\phi} + W(\phi) = 0. \tag{16}$$

Then the slow-roll parameters are defined

where $W(\phi) = -\frac{v(t)^2 f_1 \alpha}{2e^{\alpha \phi(t)}} + \frac{\chi_2 f_2 \alpha v(t)^4}{2e^{2\alpha \phi(t)}}$, i.e. $W(\phi) \neq U'_{eff}$, for $U_{eff}(\phi) = \frac{1}{4} \frac{(f_1 e^{-\alpha \phi} + M_1)^2}{\chi_2 (f_2 e^{-2\alpha \phi} + M_2) - 2M_0}$.

Then we get the following 2 cases

Case 1: $v(t)^2 A(t) >> 1$:

$$\ddot{\phi} - \frac{1}{2}\alpha\dot{\phi}^2 + \left(3H + 2\frac{\dot{v}}{v}\right)\dot{\phi} - \frac{\alpha e^{-\alpha\phi}}{2A(t)}\left(f_1 - \chi_2 f_2 v^2 e^{-\alpha\phi}\right) = 0.$$
(17)

Case 2: $v(t)^2 A(t) << 1$:

$$\ddot{\phi} + 3H\dot{\phi} - \frac{v^2\alpha e^{-\alpha\phi}}{2}\left(f_1 - \chi_2 f_2 v^2 e^{-\alpha\phi}\right) = 0.$$
(18)

Using the asymptotic values of v(t) for $p_u \rightarrow 0$:

$$v_{p} = \sqrt{\frac{f_{1}e^{-\alpha\phi} + M_{1} - \frac{1}{2}\chi_{2}b_{0}e^{-\alpha\phi}\dot{\phi}^{2}}{\chi_{2}(f_{2}e^{-2\alpha\phi} + M_{2}) - 2M_{0}}}.$$
(19)

If $v_{pb} = v_p(b_0 \rightarrow 0)$, the connection with the effective potential becomes clear: $v_{pb}^2 = \frac{4U_{eff}}{f_1 e^{-\alpha\phi} + M_1}$.

The derivative of the effective potential with respect to ϕ written in terms of the effective potential and the velocity v_{pb} becomes:

$$U_{eff}' = -\frac{2U_{eff}\alpha e^{-\alpha\phi}}{f_1 e^{-\alpha\phi} + M_1} \left(f_1 - \frac{4U_{eff\chi_2 f_2 e^{-\alpha\phi}}}{f_1 e^{-\alpha\phi} + M_1} \right) \right) \approx \\ \approx -\frac{v_{pb}^2}{2} \alpha e^{-\alpha\phi} \left(f_1 - v_{pb}^2 f_2 \chi_2 e^{-\alpha\phi} \right). (20)$$

Then, in the limit $v \rightarrow v_{pb}$, the equations reduce to: Case 1:

$$\ddot{\phi} + \frac{1}{2} \left(\frac{U'_{eff}}{U_{eff}} + \frac{\alpha e^{-2\alpha\phi} \chi_2 f_2 v_{pb}^4}{2U_{eff}} - \alpha \right) \dot{\phi}^2 + 3H\dot{\phi} + \frac{1}{v_{pb}^2 A(t)} U'_{eff} = 0.$$
(21)

Case 2:

$$\ddot{\phi} + 3H\dot{\phi} + U'_{\text{eff}} = 0.$$
⁽²²⁾

One can see that in Case 2, we are able to approximate with the standard equation, in Case 1 - no.

Numerical analysis



Figure: Left - Case 1 ($\chi_2 = 1$, $M_0 = -0.04$, $M_1 = 1.5$, $M_2 = 0.001$) for parameters { α , b_0 , p_u , f_1 , f_2 } = {1, 0.027, 7.7 × 10⁻⁹, 7, 10⁻³}. Right - Case 2 in case 2 ($\chi_2 = 4 \times 10^{-5}$, $M_0 = -0.01$, $M_1 = 0.763$, $M_2 = 4$). for parameters { α , b_0 , p_u , f_1 , f_2 } = {0.64, 1.41 × 10⁻⁷, 6.5 × 10⁻²⁴, 10⁻⁴, 10⁻⁸}. On the plots, one can see T_1 (solid lines), T_2 (dotted lines), T_3 (dash lines), T_4 (dash-dot lines).

$$T_{1} = v(t)^{2} b_{0} \chi_{2} e^{-\alpha \phi(t)} / 2 = v(t)^{2} A(t), T_{2} = v(t)^{2} b_{0} \dot{\phi}(t)^{2} \alpha \chi_{2} e^{-\alpha \phi(t)} / 4, \quad (23)$$

$$T_{3} = 3v(t)^{2} b_{0} \chi_{2} H e^{-\alpha \phi(t)}, T_{4} = v(t) b_{0} \chi_{2} \dot{v}(t) e^{-\alpha \phi(t)}, \quad (24)$$

$$T_5 = -\nu(t)^2 f_1 \alpha e^{-\alpha \phi(t)} / 2 + \chi_2 f_2 \alpha \nu(t)^4 e^{-2\alpha \phi(t)} / 2, \qquad (25)$$

Evolution of some physical parameters in the two cases



Figure: With solid lines (Case 1) and dashed (Case 2), we display the Hubble parameter H, the darkon field v(t) and its first derivative $\dot{v}(t)$.

The *H*-term dominates Case 2 but does not dominate Case 1 until late times.

As expected $\dot{v} \rightarrow 0$ during late-time inflation, however, in the early times, terms depending on v and \dot{v} cannot be ignored.

Stability of the solution with respect to ϕ_0



Figure: Using the parameters for Case 2, we plot a) the inflaton ϕ and b) the second derivative of the scale factor $\ddot{a}(t)$ for $\phi(0) = -17.9$ (dashed line), $\phi(0) = -18$ (solid line), $\phi(0) = -18.1$ (dot-dashed line). c) the dependence $\phi(t)$ and $\dot{\phi}(t)$ for $\dot{\phi}(0) = 0, \pm 10^4$ where the solid line corresponds to zero initial velocity.

Comparison of U'_{eff} and T_5



Figure: Comparison of the term T_5 (dash) with the derivative of the effective potential U'_{eff} (solid) in the two cases. Note, here the x-axis for Case 1 stops before t = 2 in order to zoom on the interval in t where the difference is the most significant

Numerical integration

In summary we observe that:

- **()** Independent of the value of $\phi(0)$, there is a period for which ϕ increases in absolute value i.e. it climbs up the slope of the effective potential
- 2 This effect becomes more pronounced the more we increase in absolute value $\phi(0)$
- The effect does not depend on \u00fc(0). That is to say that this effect is not connected with the inflaton gaining kinetic energy so that it can climb the slope.
- The time during which this happens puts it in the interval when the effective potential is not a good approximation of the potential term.

The effective potential might not be a good approximation!

- We reconstruct the effective potential U_{eff}^{num} from T_5 trough the means of numerical integration. I.e. we assume that $U_{eff}^{num} \sim \int T_5(\phi) d\phi$.
- We use numerical integration of the data points [φ(t_i), T₅(t_i)] with a modified Simpson's rule adapted to work in Maple with 1000 datapoints.
- The constant of integration has been determined by comparing the numerical potential and the effective one at late times.



The results, Staicova, arXiv:1808.08890

- The effect of "climbing up the slope" does not appear in the numerically integrated potential term.
- The integrated potential coincides with the effective potential after some moment in time, i.e. the effective potential indeed a very good approximation of the potential term.
- The deviation between the two is seen during the early times of the integration.

Analogue with the Lagrange points:

$$\begin{split} \ddot{r} + 2(\Omega x \dot{r}) &= -\nabla (V_g(r) - 1/2\Omega^2 r^2) \\ V_g(r) &= -\frac{GM_1}{\sqrt{(x+r1)^2 + y^2}} - \frac{GM_2}{\sqrt{(x+r2)^2 + y^2}} \end{split}$$



Conclusions:

1. We have numerically confirmed that the multi-measure model can be applied to the inflaton+darkon case.

2. We have shown that it is not possible to start from the left plateau and to obtain physically realistic solutions

- 3. There is friction term which stops the evolution of the inflaton
- 4. The theory can produce "realistic" Universe if evolution starts from the slope.

5. The effective potential is a good approximation to the actual potential term only after certain moment.

Summary of the viable (left) and nonviable (right) Scalar-Tensor theories after GW170817 [Ezquiaga and Zumalacárregui (2017)]



arXiv: 1710.05901, arXiv: 1712.06556

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